# LOCAL MENTAL EFFORT VS. GLOBAL COMPENSATION: **PERSPECTIVES FROM A NEUROCOGNITIVE MODEL OF VIGILANT ATTENTION**

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### INTRODUCTION

- Performance in sustained attention tasks, such as the Psychomotor Vigilance Test (PVT; Dinges & Powell, 1985), decreases due to cognitive and physical fatigue.
- Recent simulations of the PVT (Veksler & Gunzelmann, 2018) do not account for observed increases in vigilant effort toward the end of the task (i.e., end-spurt effects) and have yet to integrate neural and behavioral data.
- Additionally, recent EEG studies suggest a distributed attentional system, wherein PVT performance is influenced by simultaneous contributions of local (bottom-up) stimulus-driven activation and global (topdown) goal-driven facilitation (Buschman & Miller, 2007).
- We developed an ACT-R model of the PVT that uses frontal  $\gamma$  and  $\beta$  power spectral density (PSD) estimates to constrain parameters that influence behavioral task performance.
- Specifically,  $\gamma$  values constrain production utility values (U) and  $\beta$  values constrain utility thresholds (UT), relating to arousal and compensation, respectively.
- We hypothesize that  $\beta$  PSD values correspond to global compensation while  $\gamma$  PSD values correspond to local efforts, such as the end-spurt.

## **PSYCHOMOTOR VIGILANCE TEST**

- The PVT has been used extensively in fatigue research.
- Participants asked to respond as soon as numbers appear on screen.
- Numbers reflect milliseconds since stimulus onset and will stop when a response is given.



- Length of time between previous trial and onset of stimulus (ITI) randomly sampled between 2 and 10 s.
- Reaction times (RTs), false start rates, and lapse rates increase with fatigue.

## **OBSERVED DATA**

- 34 young adults ( $M_{age} = 22.6$ ,  $SD_{age} = 4.1$ ) recruited through the University of Dayton Research Institute.
- Participated in a single 2-hour EEG session.
- The PVT lasted 10 m (approximately 100 trials).
- We computed power spectral density for frontal  $\gamma$  and  $\beta$ .
- Generally, RTs, response error, and  $\beta$  PSD estimates increase across trials while  $\gamma$  PSD estimate decrease.
- Importantly, some participants demonstrated end-spurt efforts in the last 2 m of the task.

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## **COMPUTATIONAL MODEL**



### ACT-R

•	ACT-R (Anderson et al., 2004) provides a rich environment for simulating attention and fatigue with high temporal resolution.	• L 2 t
•	Models traversals between discrete behavioral states, and changes in transition probabilities are captured using moderators on performance variables.	•
•	The actions that are chosen are those with the highest	•

The actions that are chosen are those with the highest utilities (U), which are based on an initial utility value ( $\varepsilon$ ), match to present state (*mp*), and random noise (e):

$$U_{p,s}(n) = v - mp_{p,s} + \varepsilon$$

- A utility threshold (UT) prevents actions with low activations from being chosen.
- Behavior is chosen from all above-threshold actions:





#### Fatigue Moderation

\_ike previous implementations (Gunzelmann et al., 2009; Veksler & Gunzelmann, 2018), the model traverses 3 states: *Wait*, *Attend*, and *Respond*.

previous model, performance However, unlike decrements are not solely based on time-on-task and the effects of brief lapses in attention (microlapses, *ml*).

Utility values are affected by an initial utility value, microlapse penalty ( $\lambda$ ), and scaling of  $\gamma$  PSD using a modified decibel conversion:

$$U_{i} = v \cdot \lambda^{N_{ml}} \cdot \log_{b} \left( \frac{\gamma_{i}}{\mu_{\gamma_{1:k}}} \right) + 1$$

Similarly, utility thresholds are a function of an initial utility threshold ( $\tau$ ) and scaling of  $\beta$  PSD estimates:

$$UT_{i} = \tau \cdot \left[ log_{b} \left( \frac{\beta_{i}}{\mu_{\beta_{1:k}}} \right) \right]^{-1} + 1$$

Right: RT distributions for observed (blue) and simulated (yellow) data.

Summarv statistics o recovered parameters and fit statistics across individuals using the Fatigue and Power models.

#### Mode Fatigue

Power



### SIMULATION RESULTS

• We compared performance between a previous model of the PVT (the "Fatigue" model; Veksler & Gunzelmann, 2018) and the proposed model (the "Power" model).

• We estimated parameters using Bayesian techniques.

• The Power model accounts for more overall information than the Fatigue model and provided a better fit to observed data for 31/34 participants.

• Simulated RT distributions generated from the new simulation closely match observed RT distributions.



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	U	T	λ	Y	ρ	К	AIC	BIC
е	4.58	3.04	0.90	0.057	-0.19	-0.21	1174.54	1178.12
	(0.11)	(0.09)	(0.01)	(0.001)	(0.005)	(0.004)	(16.42)	(16.42)
r	3.97	1.86	0.92	0.058	-	-	962.51	965.28
	(0.29)	(0.15)	(0.01)	(0.002)	-	-	(25.83)	(25.83)

#### DISCUSSION

 Models using vigilant attention approximated from frontal  $\gamma$  and  $\beta$  PSD provide a better fit to observed PVT data than previous fatigue models.

•  $\beta$  PSD estimates reflect behaviors that offset the effects of fatigue across the PVT task.

•  $\gamma$  PSD estimates reflect localized efforts to improve performance across short periods of time, e.g., end-spurt efforts.

 Consistent with accounts that suggest that lowerfrequency bands broadcast a global (top-down) strategy while higher-frequency bands support local (bottom-up) interactions needed to enhance stimulus representations (Buschman & Miller, 2007), and consistent with multiprocess theories of vigilant attention.

• Overall, our simulation demonstrates the efficacy of aggregate and individual PSD as meaningful parameters in simulations of the PVT.

• These models provide an important step in developing computational models that simultaneously account for neural and behavioral data.

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